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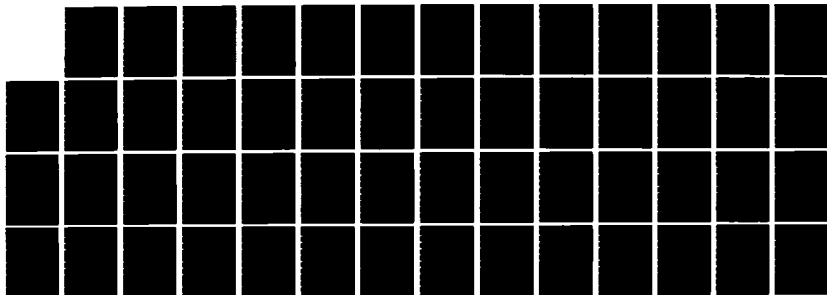
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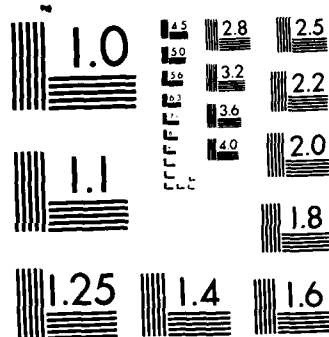
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Surface Plasmon Dispersion Relation and Local Field Enhancement
Distribution For a Deep Sinusoidal Grating

by

Dan Agassi and Thomas F. George

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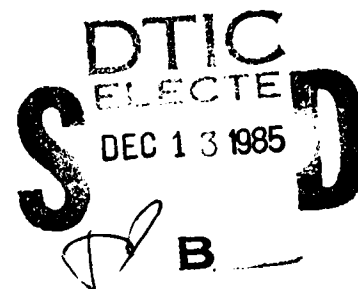
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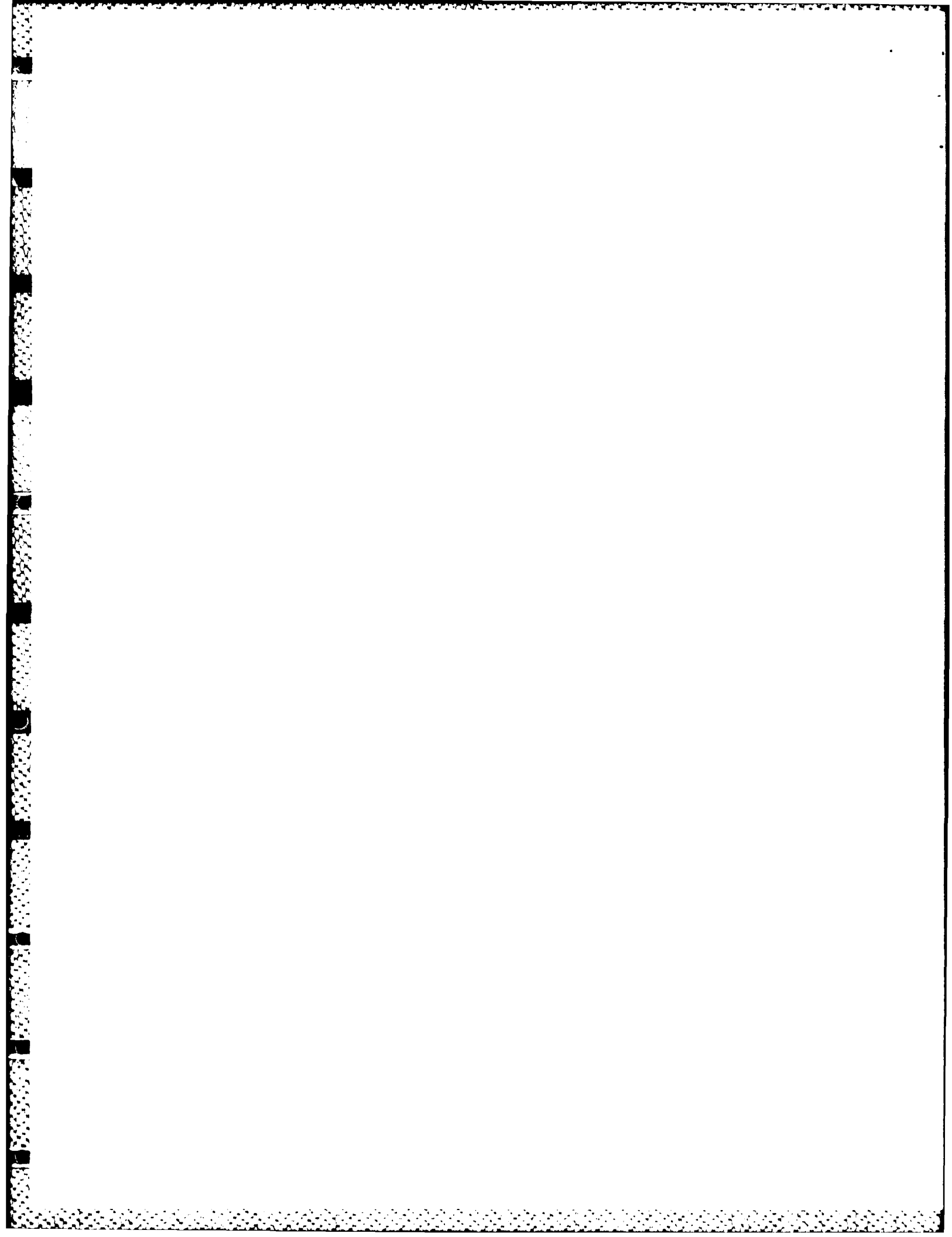
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SURFACE PLASMON DISPERSION RELATION AND LOCAL FIELD ENHANCEMENT
DISTRIBUTION FOR A DEEP SINUSOIDAL GRATING

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Abstract

Two features of light scattering from a deep lossless metallic sinusoidal grating are considered in the limit $g/d \rightarrow \infty$, where g and d are the height and periodicity of the grating, respectively. It is found that the surface plasmon dispersion relation is comprised of two flat bands with a frequency gap $\Delta\omega/\omega_p = (\sqrt{2} - 1)/2$, where ω_p is the volume plasmon frequency. For the local field enhancement distribution at the grating's surface, the results show the existence of two qualitatively distinct domains, i.e., $\lambda \gg d$ and $\lambda \ll d$, where λ denotes the radiation wavelength. In both domains, however, the local field enhancement is larger at the bottom of the troughs than at the top of the peaks. The dressed Rayleigh expansion is used throughout for the analysis.

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1. Introduction

Light scattering from a deep grating, i.e., a grating for which $\beta = 2\pi g/d \gg 1$ where g and d are the maximum (and minimum) extension and periodicity of the grating, respectively (see Fig. 1), is a relatively newly studied physical phenomenon. Moderately deep gratings can now be fabricated, e.g., by photodissociation of organometallic molecules at a substrate.^{1,2} The extremely deep grating case ($\beta \rightarrow \infty$), which is at the focus of this work, should be considered as an idealized limit. This limit is complementary to the shallow grating limit ($\beta \ll 1$), which is realized in many physical systems and has been extensively explored over the last century.

The extremely deep grating regime is qualitatively different from the shallow grating regime.³ It can be characterized as a strong coupling situation in the sense that the many possible Bragg reflections (Fig. 1) interfere strongly with each other, giving rise to a scattered field of new qualitative features. By contrast, the shallow grating regime can be analyzed in terms of a few 'weak' (in comparison with the specular reflected light) Bragg reflections. Unfortunately, attempts to solve the Maxwell equations for deep gratings using the so-called Rayleigh expansion, which works beautifully when $\beta \ll 1$, have encountered numerical instabilities.⁴ These difficulties have motivated the introduction of several alternative schemes,^{1,5,6} all of which, however, share difficulties in the $\beta \gg 1$ regime. In another paper³ we have suggested yet another scheme -- dubbed as the dressed Rayleigh expansion -- which overcomes these difficulties. We have also explicitly demonstrated³ that this

scheme converges for a sinusoidal grating (SG) of arbitrary β . Here we apply the dressed Rayleigh expansion to study two aspects of light scattering from a very deep metallic SG grating, namely, the surface plasmon (SP) dispersion relation and the distribution of the local field enhancement along the grating's surface.

Our results are valid in the $\beta \rightarrow \infty$ limit and under several approximations which are spelled out as we go along. For the SP dispersion relation we find two flat bands (see Fig. 2). The frequency band gap $\Delta\omega$ is given by $\Delta\omega/\omega_p = \frac{\sqrt{2}-1}{2} = .207$, where ω_p is the volume-plasma frequency of the metal. We interpret the two bands to reflect two classes of localized surface modes -- those for which the field maxima are in the peaks and in the troughs of the grating respectively. A similar situation occurs in standard band structure studies. The fact that we obtain dispersion bands rather than the usual dispersion curves for $\beta \ll 1$ is in keeping with studies of moderately deep gratings, $g/d \leq 1$,^{7,8} where it has been observed for the latter that as g/d increases new SP dispersion branches pop out in pairs at the $\omega/\omega_p = 1/\sqrt{2}$ line. As g/d keeps increasing, one branch of the pair is pushed upward and the other branch is pushed downward to be followed by the emergence of a new pair of branches. Since the available frequency interval is confined both from below ($\omega/\omega_p = 0$) and from above ($\omega/\omega_p = 1$), the accumulation of the branches into bands as $\beta \rightarrow \infty$ may be expected. However, the particular band gap and widths we derive [Eqs. (4.4) and (4.5)] may be, in part, an artifact of our approximations. SP dispersion bands have also been derived for an infinitely large stack of thin metallic films.⁹

We also evaluate a simple figure-of-merit representing the local field enhancement distribution. The local field enhancement R is defined as $R = |\vec{E}/\vec{E}_{inc}|^2$, where \vec{E} is the total electric field and \vec{E}_{inc} is the incident electric field.^{6,10} The value and distribution of R are of prime importance in determining optical and chemical processes near the grating.¹¹ To remain within reach of a simple analytical result, we evaluate only $R(T/B) = |R(T)/R(B)|^2$, where the points T (top) and B (bottom) are defined in Fig. 1, and the incident light is normal to the grating. The result [Eq. (5.3)] indicates the existence of two distinct regimes, i.e., $\lambda \gg d$ and $\lambda \ll d$, where λ is the wavelength of the incident light. The $R(T/B)$ ratio in the former is smaller than in the latter, and in both regimes $R(T/B) \sim 1/\beta$. These findings are understood in terms of the following physical picture: The incident field induces the electrons in the metal into an oscillating motion, and the electrons respond. Since the grating is deep, the motion of the electrons at the grating's peak is inhibited by the grating's boundaries, and much less so at the troughs' bottoms, and hence $R(T/B) \ll 1$. The distinction between the $\lambda \gg d$ and $\lambda \ll d$ regimes can also be understood in the same vein: The response of the electrons at the bottoms is inhibited by the grating's boundaries and hence depends only mildly on λ . The response of the electrons at the peak's top, however, is strongly dependent on λ : For $\lambda \gg d$, these electrons respond very poorly due to the confinement of the grating's boundaries, while, as λ ever decreases, the top electrons can respond ever more efficiently. Consequently, the ratio $R(T/B)$ is larger for $\lambda \ll d$ than for $\lambda \gg d$.

The paper is organized as follows: We introduce in Section 2 the dressed Rayleigh expansion³ in the context of the SG. In Section 3 we present the central approximations which enable a simple solution for the light scattering problem in the asymptotic limit $\beta \rightarrow \infty$. The results of Section 3 are then applied in Section 4 to analyze the SP dispersion relations and in Section 5 to evaluate the local field enhancement distribution for a particularly simple configuration. Section 6 is a discussion and summary.

2. Dressed Rayleigh Expansion and Sinusoidal Grating

We introduce in this section the dressed Rayleigh expansion³ and the pertinent formulas of the SG. As has been demonstrated elsewhere, the dressed Rayleigh expansion converges for an SG arbitrary β and therefore provides a convenient framework to analyze the $\beta \rightarrow \infty$ limit. All expressions in this section are exact. The notations throughout are defined in Fig. 1

The dressed Rayleigh expansion for the electromagnetic fields is³

$$\begin{aligned} \vec{E}_0(x, z) &= \sum_{\ell=-\infty}^{\infty} \{ \gamma_0(\ell) \hat{p}_{0,-}(\ell) e^{i[k_\ell x - W_0(\ell)(z+g)]} \\ &\quad + \alpha_0(\ell) \hat{p}_{0,+}(\ell) e^{i[k_\ell x + W_1(\ell)(z+g)]} \} \\ \vec{E}_1(x, z) &= \sum_{\ell=-\infty}^{\infty} \gamma_2(\ell) \hat{p}_{1,-}(\ell) e^{i[k_\ell x - W_1(\ell)(z-g)]} \end{aligned} \quad (2.1.a)$$

and

$$\begin{aligned}\vec{B}_0(x, z) &= \frac{k(0)}{k} \hat{s} \sum_{l=-\infty}^{\infty} \left\{ \gamma_0(l) e^{i[k_l x - W_0(l)(g+z)]} \right. \\ &\quad \left. + \alpha_0(l) e^{i[k_l x + W_0(l)(g+z)]} \right\} \\ \vec{B}_1(x, z) &= \frac{k(1)}{k} \hat{s} \sum_{l=-\infty}^{\infty} \gamma_1(l) e^{i[k_l x - W_1(l)(g-z)]}, \quad (2.1.b)\end{aligned}$$

where

$$\gamma_0(l) = \delta_{l,0} E_{0,p}^- e^{+iW_0(l)g} \quad (2.2)$$

and

$$k(i) = \sqrt{\epsilon_i} k, \quad k = \omega_0/c, \quad k_G = 2\pi/d$$

$$W_1(l) = [k^2(i) - k_l^2]^{1/2}, \quad k_l = k_{||} + lk_G$$

$$\begin{aligned}\hat{p}_{i,\pm}(l) &= \frac{1}{k(i)} [k_l \hat{z} \mp W_1(l) \hat{x}], \quad \hat{s} = \hat{x} \times \hat{z} \\ &\text{for } i = 0, 1. \quad (2.3)\end{aligned}$$

In (2.1) - (2.3) the subscripts of the fields refer to the domains (0 or 1), the time dependence of the fields is assumed to be $e^{-i\omega_0 t}$, $k_{||}$ is the \vec{x} -momentum component label of the field, \hat{x} , \hat{z} and \hat{s} are unit operators in the obvious three directions, E_{0p}^- is the arbitrary amplitude of the p-polarized incident light normal to the grating's grooves, and we always choose $\text{Im}[W_1(l)]$ or $\text{Re}[W_1(l)] \geq 0$. The height g (positive) is half the maximum z -extension of the grating (Fig. 1), and the central parameter β is again

$$\beta = gk_G. \quad (2.4)$$

The dressed Rayleigh expansion coefficients satisfy

$$\begin{aligned}\sum_{l=-\infty}^{\infty} M_{m,l} \alpha_0(l) &= \mu(m) \\ \sum_{l=-\infty}^{\infty} N_{m,l} \gamma_1(l) &= \nu(m), \quad (2.5.a)\end{aligned}$$

where the matrix \underline{M} , for instance, can be dubbed as the "Fresnel matrix".

It is given by

$$\begin{aligned} M_{m,l} &= e^{i(W_1(m) + W_0(l))g} M_{m,l}^B, \quad \mu(m) = e^{iW_1(m)g} \mu^B(m) \\ N_{m,l} &= e^{i(W_0(m) + W_1(l))g} N_{m,l}^B, \quad \nu(m) = e^{iW_0(m)g} \nu^B(m), \end{aligned} \quad (2.5.b)$$

and

$$\begin{aligned} M_{m,l}^B &= \frac{W_0(l)W_1(m) + k_l k_m}{W_0(l) - W_1(m)} i^{m-l} J_{m-l}[g(W_0(l) - W_1(m))] \\ N_{m,l}^B &= \frac{W_1(l)W_0(m) + k_l k_m}{W_1(l) - W_0(m)} i^{m-l} J_{m-l}[g(-W_1(l) + W_0(m))] \\ \mu^B(m) &= \frac{-W_0(0)W_1(m) + k_0 k_m}{W_0(0) + W_1(m)} i^m J_m[-g(W_0(0) + W_1(m))] E_{0p}^- \\ \nu^B(m) &= \frac{2\varepsilon_0 \varepsilon_1}{\varepsilon_1 - \varepsilon_0} W_0(m) \delta_{m,0} E_{0p}^-, \end{aligned} \quad (2.6)$$

where J_ν denotes the Bessel function of order ν .

It has been shown elsewhere³ that the set of equations (2.5) can be safely truncated at a maximum $|l|$ -value L of the order β , since the matrix elements of \underline{M} decay exponentially with l or m and become insignificant beyond that point. A more detailed examination reveals that the important matrix elements of \underline{M} are distributed in two lobes: one lobe is for m 'small' and $|l|$ 'large' and the other for l 'small' and $|m|$ 'large'. The diagonal terms diminish exponentially with $l = m$ faster than either lobe's length.

Once the set of equations (2.5) is solved, all properties of the scattered fields are known. The difficulty when $\beta \rightarrow \infty$, however, is that the relevant matrix \underline{M} (or \underline{N}) is very large and highly non-diagonal. We

introduce in the next section an asymptotic approximate solution of (2.5) and then explore its implications with regard to the SP dispersion relation and light scattering.

3. Approximate Solution for $\beta \gg 1$

To discuss the fields scattered by the grating, it is necessary to invert the Fresnel matrix \underline{M} [Eq. (2.5)], which has an effective dimensionality on the order of β when $\beta \gg 1$. Obviously to gain insight we need to introduce further simplifying approximations. The construction of a simple approximation to \underline{M}^{-1} is the content of this section. The sequence of approximations below that lead to the final result [Eqs. (3.8)-(3.10)] assumes that $\beta \gg 1$, i.e., very deep gratings. At some points we resort to additional approximations motivated by the gained mathematical simplicity. We believe that the plausibility of the results derived in Sections 4 and 5 based on the approximate \underline{M}^{-1} vindicate the approximations. To gain perspective on the $\beta \gg 1$ regime considered here, we give the analysis pertaining to shallow gratings in Appendix A.

An attractive feature of \underline{M} , or \underline{M}^B , is its partial separability in the "m" and "l" indices [Eq. (2.6)]. As will become obvious shortly, separable matrices are convenient mathematically. We are therefore motivated to devise a separable approximation to the other factors in (2.6), in particular to the Bessel function factor. This turns out to be possible provided $|m|$, $|l|$ and $|m-l|$ are very large compared to unity, which is the case for most of the elements of the highly non-diagonal matrix \underline{M} .

Using (2.6) the ensuing quasi-separable approximation is (Appendix

B)

$$M_{m,l}^{(S)} = C_0 \frac{1}{[W_0(l) - W_1(m)]^{3/2}} i^{m-l} [W_0(l)W_1(m) + k_l k_m] \\ \times e^{ig[W_0(l) + W_1(m)]} \{e^{i\phi} + e^{-i\phi}\}, \quad (3.1.a)$$

where

$$C_0 = \sqrt{\frac{k_G}{2\pi}} \frac{1}{(1 + \beta^2)^{1/4}} \\ \phi = \frac{n(\beta)}{k_G} [W_0(l) - W_1(m)] - \left[\frac{m-l}{2} + \frac{1}{4}\right]\pi \\ n(\beta) = \sqrt{1 + \beta^2} + \ln[\beta/(1 + \sqrt{1 + \beta^2})] \quad (3.1.b)$$

The above is valid for $|m|, |l|, |m-l| \gg 1$. It can be easily checked by comparison with (2.6) that (3.1) provides a surprisingly good approximation even for the diagonal element $M_{l,l}$.

Note that $M^{(S)}$ has a separable form except for the denominator $[W_0(l) - W_1(m)]^{3/2}$. This is to be expected since a fully separable form for $M^{(S)}$ does not possess an inverse. To maintain the simplicity of a separable approximation on the one hand and yet to secure the existence of a simple inverse on the other hand, we introduce the following additional approximation: Consider first the off-diagonal matrix elements of $M^{(S)}$. These elements are grouped into two lobes (Section 2), i.e., when $|m|$ is 'small' and $|l|$ is 'large', and vice versa. When $|m|$ is 'small' and $|l|$ is 'large', for example, the fastest $|l|$ -changing factor in $M^{(S)}$ is the exponential [Eq. (3.1)]. Consequently, the above mentioned now separable denominator, which changes with $|l|$ much more

slowly, acts approximately as a normalizing factor. It can be therefore approximated by a suitably chosen constant, denoted by C_1 . For the sake of simplicity, we further approximate $[W_0(l)-W_1(m)]^{3/2} = C_1$ for both the $|m| \ll |l|$ and $|l| \ll |m|$ elements. The diagonal elements of $M^{(S)}$ comprise the complementary (minority) group of elements to the off-diagonal elements just discussed. In this case, the above argument concerning the fastest $|l|=|m|$ -changing factor in $M^{(S)}$ is still valid. However, the corresponding constant approximating the non-separable denominator is obviously quite different, i.e., $[W_0(l)-W_1(l)]^{3/2} = C_2$. The foregoing discussion suggests therefore the approximation

$$M_{m,l} \approx M_{m,l}^{(S)} = D_l \delta_{m,l} + V_{m,l}, \quad (3.2)$$

$$V_{m,l} = C i^{m-l} [W_0(l)W_1(m) + k_l k_m] e^{ig[W_0(l) + W_1(m)]} \{e^{i\phi} + e^{-i\phi}\}$$

$$C = C_0/C_1, \quad (3.3)$$

and C_1 has been defined in the discussion above.

The diagonal elements D_l in Eq. (3.2) depend, of course, on the choice of C_1 and C_2 . However, regardless of the particular choice, due to the convergence factors $e^{ig[W_0(l) + W_1(m)]}$, the number of significant diagonal elements is of the order of unity. Therefore, there are only very few significant diagonal terms in comparison with the number of off-diagonal terms, yet if they are neglected, Eq. (3.2) ceases to have an inverse. We have therefore a situation where a few diagonal terms are not important in terms of physical results, yet due to the particular mathematical structure (separability) it is necessary to keep them to assure the existence of an inverse. Under such

conditions, it is probably immaterial as to how the diagonal terms are chosen, provided the calculated observable does not depend on the specifics of the choice. We therefore simplify Eq. (3.2) further by the approximation $D_\ell = D$, where D is a very small number of the order $e^{-\beta}$ or less. Again, to be consistent with the arguments above, we can use the ensuing approximation only to calculate observables that do not depend on D , such as those analyzed in the next two sections. We would like to emphasize that the $D_\ell = D$ approximation is not essential, i.e., it is possible to invert Eq. (3.2) as it stands. The substantial simplification gained by adopting this approximation, however, warrants an examination. Therefore, Eq. (3.2) is replaced by

$$M_{m,\ell} = D\delta_{m,\ell} + V_{m,\ell} \quad (3.4)$$

where D is a very small number of the order $e^{-\beta}$.

The inversion of Eq. (3.4) can be obtained now in a straightforward manner. Note from Eq. (3.3) that V is comprised of four separable terms,

$$V_{m,\ell} = \sum_{j=1}^4 a_j(m) b_j(\ell), \quad (3.5)$$

where the factors a_j and b_j are extracted from Eqs. (3.1.b) and (3.3) [see Appendix C, Eq. (C.2)]. The form of Eq. (3.5) has the attractive property that V to the n -th power is given by

$$(V^n)_{m,\ell} = \sum_{i,j=1}^4 a_j(m) [A^{n-1}]_{i,j} b_j(\ell), \quad (3.6)$$

where the auxiliary interaction matrix A is of dimension 4 with the elements

$$A_{i,j} = \sum_{\ell=-\infty}^{\infty} b_i(\ell) a_j(\ell). \quad (3.7)$$

The auxiliary matrix \underline{A} (Appendix C) plays a central role in all subsequent manipulations. Consequently, expanding the inverse of Eq. (3.4) in a geometric series and using Eq. (3.6) yields

$$\begin{aligned} (M^{-1})_{m,l} &= \frac{1}{D} \delta_{m,l} - \frac{1}{D^2} \sum_{i,j=1}^4 a_i(m) \left(\left[1 + \frac{1}{D} \underline{A} \right]^{-1} \right)_{i,j} b_j(l) \\ &= \frac{1}{D} \left[\delta_{m,l} - \sum_{i,j=1}^4 a_i(m) [\underline{A}^{-1}]_{i,j} b_j(l) \right] \quad (3.8) \end{aligned}$$

The second line in Eq. (3.8) follows since $\langle |\underline{A}| \rangle / D$, where $\langle |\underline{A}| \rangle$ is a typical average value of the elements of \underline{A} [see (C.18) and (C.20)] and D is an extremely small number.

The approximate inverse (3.8) is a key result of this work. The unknown parameter D appears as a multiplicative factor, implying that (3.8) can be used only to evaluate ratios so that D drops out from the final result. Note that (3.8) embodies the reduction of an inversion problem of a $\beta \times \beta$ matrix to the inversion of a 4×4 matrix.

Based on the analytical expressions for the matrix elements of \underline{A} (Appendix C), the inverse \underline{A}^{-1} can be further simplified. The key remark is that when $\beta \rightarrow \infty$, the matrix elements denoted by " α " in Table 1 are substantially smaller than the rest of \underline{A} [see (C.11) and following discussion] and therefore can be neglected. Consequently,

$$\begin{aligned} \det(\underline{A}) &= \det(\underline{A}_\gamma) \det(\underline{A}_\delta) \\ \det(\underline{A}_\gamma) &= A_{1,2} A_{3,4} - A_{1,4} A_{3,2} \\ \det(\underline{A}_\delta) &= A_{2,1} A_{4,3} - A_{2,3} A_{4,1} \quad (3.9) \end{aligned}$$

where the symbol "det" indicates a determinant, and

$$\underline{A}^{-1} = \frac{1}{\det(\underline{A}_\gamma)} \begin{pmatrix} 0 & 0 & 0 & 0 \\ A_{3,4} & 0 & -A_{1,4} & 0 \\ 0 & 0 & 0 & 0 \\ -A_{3,2} & 0 & A_{1,2} & 0 \end{pmatrix} + \frac{1}{\det(\underline{A}_\delta)} \begin{pmatrix} 0 & A_{4,3} & 0 & -A_{2,3} \\ 0 & 0 & 0 & 0 \\ 0 & -A_{4,1} & 0 & A_{2,1} \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad (3.10)$$

+ mixed γ and δ terms

The simplicity of (3.9) and (3.10) in conjunction with (3.8) is most gratifying. It indicates an expectation that in the limit $\beta \gg 1$, as in the $\beta \ll 1$ limit, the physics should simplify. All that is needed to obtain \underline{M}^{-1} are eight matrix elements, combined in the simple form of (3.10)!

4. Surface Plasmon Dispersion Relation

Surface plasmon excitations are collective, surface-attached oscillations of the metal's electron gas, well studied in the context of flat metallic surfaces and shallow gratings.^{7,8} For the case of a shallow grating, the dispersion relation is comprised of many branches (for a lossless metal, as assumed here throughout) which are arranged in pairs above and below the line $k/k_p = \sqrt{2}$, where $k_p = \omega_p/c$ and ω_p is the volume plasmon frequency. In this section we derive the dispersion relation for the $\beta \rightarrow \infty$ limit, i.e., pertaining to very deep gratings.

The emergence of pairs of dispersion relation branches when $\beta \neq 0$ can be understood using arguments employed in interpreting the opening of a band gap for electrons moving in a periodic ionic potential.¹² In

the latter case there are two interfering combinations of unperturbed electron wave and the umklapp-reflected wave. Since one combination is centered at the ions' sites and the other between ions, the associated energy of these two combinations are split and a band gap opens. In the present case the Bragg reflections play the role of the umklapp processes and the unperturbed electron waves -- by the flat-surface SP mode (see Appendix A) and hence the pairs of dispersion branches. We expect this type of dichotomy to persist for $\beta \rightarrow \infty$. The remaining issue is therefore how do these pairs of branches accumulate for $\beta \rightarrow \infty$, given that the available frequency domain is bounded from below by $\omega/\omega_p = 0$ and from above by $\omega/\omega_p = 1$.

By definition, the SP excitations decay exponentially in both z -directions, Fig. 1, i.e., these are excitations for which $E_{0p}^- = 0$ in (2.6). Consequently, to have a non-trivial solution of the Fresnel equations (2.5), the condition

$$\det(\underline{M}) = 0 \quad (4.1)$$

determines a function of $k(0)$ versus $k_{||}$ provided that $-k_G/2 \leq k_{||} \leq k_G/2$, i.e., $k_{||}$ is confined to the first Brillouin zone.⁷ Condition (4.1) is tantamount to finding the points where \underline{M}^{-1} does not exist (poles).

Hence, in the context of the approximate inverse (3.8), Eq. (4.1) transcribes into $\det(\underline{A}) = 0$. The determinant of \underline{A} , however, is given by (3.9) in the leading asymptotic order. Consequently, since $\det(\underline{A}_\delta) \neq 0$ outside the light cone [see Eq. (C.22)], the SP dispersion relation is simply

$$\det(\underline{A}_\gamma) = A_{1,2} A_{3,1} - A_{1,4} A_{3,2} = 0 \quad (4.2)$$

Inserting into (4.2) the explicit expressions for the matrix elements (C.20) yields

$$\begin{aligned} & \frac{[3k^2(0) + k^2(1))(k^2(0) + 3k^2(1))}{3[k^2(0) + k^2(1)]^2} \\ &= \left[\frac{\sin[L(\alpha + \gamma)]\sin[\frac{\alpha - \gamma}{2}] - \sin L[(\alpha - \gamma)]\sin[\frac{\alpha + \gamma}{2}]}{\sin[L(\alpha + \gamma)]\sin[\frac{\alpha - \gamma}{2}] + \sin[L(\alpha - \gamma)]\sin[\frac{\alpha + \gamma}{2}]} \right]^2, \quad (4.3.a) \end{aligned}$$

where $k(i) = \sqrt{\epsilon_i} k$ from (2.2) and

$$\gamma = 2\pi k / k_G$$

$$\alpha = \frac{\pi}{k_G} \{-[k^2(0) + k^2(1)]\}^{1/2}. \quad (4.3.b)$$

In (4.3.a) L is a very large number of the order β [see the discussion after Eq. (C.12)], the precise value of which is immaterial (see below).

The analysis of (4.3) is quite simple. Consider first the $k(0) \leq k_p/[1 + \epsilon_0]^{1/2}$ regime, where α and obviously γ of (4.3.b) are real and hence the RHS of (4.3.a) is real and positive. It can be easily shown that for (4.3.a) to have a solution it is necessary that $k < k_p/[3\epsilon_0 + 1]^{1/2}$. When $k(0) \geq k_p/[1 + G_0]^{1/2}$ the α -parameter is imaginary and hence the RHS of (4.3.a) is real and negative. Simple considerations show again that

to make the LHS of (4.3.a) negative it is necessary that $k < [\frac{3}{3 + \epsilon_0}]^{1/2} k_p$ in order for a solution to (4.3) to exist, it is necessary that (assuming $\epsilon_0 = 1$ for simplicity)

$$0 \leq k \leq \frac{k_p}{2}, \quad \frac{k_p}{\sqrt{2}} \leq k \leq \frac{\sqrt{3}}{2} k_p. \quad (4.4)$$

Condition (4.4), however, is also sufficient. Since $L \sim \beta \gg 1$, the RHS exhibits oscillations which are ever increasing in amplitude and

frequency as β is increased. Therefore, any k -value within the admissible ranges (4.4) generates a solution of (4.3), i.e., the dispersion relation constitutes two bands (Fig. 2). The frequency gap $\Delta\omega$ between the bands is according to (4.4)

$$\frac{\Delta\omega}{\omega_p} = \frac{\sqrt{2} - 1}{2}. \quad (4.5)$$

The results (4.4) and (4.5) describe the accumulation of dispersion branch pairs mentioned in the beginning of this section. The interpretation of the two bands is identical to that of the two members of a dispersion branch pair: The two bands are comprised, respectively, of modes in which the field is mostly localized either in the troughs or in the peaks of the grating. We cannot be sure at this point to what degree the particular band gap (4.5) and band widths are an artifact of our approximations. At the very least, (4.4) and (4.5) indicate domains of high density of dispersion-relation curves.

Note that the dispersion relation (4.3) or (4.4) does not depend on g , k_G or $k_{||}$. The independence of g or k_G can be understood as follows: If $\beta \rightarrow \infty$ is interpreted as $g \rightarrow \infty$ and d finite, then obviously the result of any observable cannot depend on g in the asymptotic region. By the same token, the limit $\beta \rightarrow \infty$ can be construed as keeping g finite but letting $d \rightarrow 0$, which leads again to the conclusion that the result cannot depend, to the leading order, on k_G . The independence of the band structure of $k_{||}$ may be an artifact of our approximations. The behavior of the matrix elements of \underline{M} near the light cone, for instance, is controlled by the $W_j(l)$ sectors [Eq. (2.2)], with the square-root feature playing an essential role (Appendix A). On the other hand, in all manipulations employed here, we expand the square root $W_1(l)$ as

$$W_1(l) = 1 \left[|k_l| - \frac{k^2(j)}{2} \frac{1}{|k_l|} \right] \quad (4.6)$$

which destroys the regaration effects near the light cone.

5. Local Field Enhancement Distribution for Normal Incident Light

As a second application of our central approximation (3.8), we turn now to the calculation of the local field enhancement distribution at the grating's surface. The local field enhancement $R(x,z)$ is defined as $R(x,z) = \left| \frac{\vec{E}_0(x,z)}{E_{0p}} \right|^2$. It measures the collective response of the electrons in the metal to an incident electromagnetic field, and is of obvious importance in determining optical and scattering processes near the grating.¹¹ To simplify the analysis, we pick the simplest configuration. We assume normal incidence of the p-polarized light and consider the ratio of the local field enhancements at the top of the peak to that at the bottom of the trough (points T and B in the notation of Fig. 1). This ratio, denoted by $R(T/B)$, is a convenient figure-of-merit describing the local field enhancement distribution. Since $R(T/B)$ is a ratio of two fields, the unknown constant D in (3.8) does not enter the final expressions.

Combining (3.8), (3.10), (2.5) and (2.1), it is straightforward to obtain for the electric field in region 0 (Fig. 1)

$$\begin{aligned} \vec{E}_0(x,z) = & \gamma_0(0) e^{i[k_0 x - W_0(0)z]} \hat{p}_{0,-}(0) \\ & + \frac{1}{D} \left\{ \sum_{l=-\infty}^{\infty} \hat{p}_{0,+}(l) e^{i[k_l x + W_0(l)z]} \mu(l) \right. \\ & \left. - \sum_{j,n=1}^4 \left\{ \sum_{l=-\infty}^{\infty} \hat{p}_{0,+}(l) e^{i[k_l x + W_0(l)z]} a_j(l) \right\} (\underline{A}^{-1})_{j,n} \left\{ \sum_{m=-\infty}^{\infty} b_j(m) \mu(m) \right\} \right\} \end{aligned}$$

$$= \vec{E}_{inc}(x,z) + \vec{E}_f(x,z) + \vec{E}_s(x,z) \quad (5.1)$$

The decomposition of $\vec{E}_0(x,z)$ in the last line of (5.1) reflects the structure of (3.10): The first term in (3.10), involving the matrix elements $A_{1,2}$, $A_{1,4}$, etc. (or class- γ elements in the terminology of Appendix C and Table 1) gives rise to field components that vary very rapidly with small changes in either k , $k_{||}$ or k_G , etc. This feature is manifested in the explicit expressions for these matrix elements [Eq. (C.20)] and has been exploited already in conjunction with the SP dispersion relation (Section 4). The corresponding component in the total field is denoted by $\vec{E}_f(x,z)$, where the subscript "f" indicates "fast". The second term in (3.10) involving the elements $A_{2,1}$, $A_{2,3}$, etc. (class- δ in the terminology of Appendix C and Table 1) changes slowly with small changes in k , $k_{||}$, etc. and gives rise to the "slow" component in the total field, denoted by $\vec{E}_s(x,z)$ in (5.1). The incident field, denoted by $\vec{E}_{inc}(x,z)$, is the first term on the LHS of (5.1). The decomposition (5.1) of the total field into a fast oscillating component $\vec{E}_f(x,z)$ and a slow envelope $\vec{E}_s(x,z)$ is expected due to the many interfering components (Bragg reflections) of which $\vec{E}_0(x,z)$ is comprised.

In terms of the decomposition (5.1), we identify the ratio of the local field enhancements at points T and B in Fig. 1 with the field envelope, or average:

$$R(T/B) = \frac{|\vec{E}_{inc}(T) + \vec{E}_s(T)|^2}{|\vec{E}_{inc}(B) + \vec{E}_s(B)|^2} = \frac{|\vec{E}_s(T)|^2}{|\vec{E}_s(B)|^2}, \quad (5.2)$$

where the arguments "T" and "B" in (5.2) indicate the coordinates of points T and B. Straightforward yet somewhat lengthy algebra (Appendix D) gives

$$\begin{aligned} R(T/B) &\approx \frac{r}{4\beta} && \text{for } r \ll 1 \\ &\approx \frac{r^7}{4\beta} && \text{for } r \gg 1 \end{aligned} \quad (5.3)$$

and ($\epsilon_0 = 1$ for simplicity)

$$r = \frac{k(0)}{k_G} = \frac{\sqrt{\epsilon_0 d}}{\lambda} = \frac{d}{\lambda} . \quad (5.4)$$

The complete expressions are given in Appendix D, whereas (5.3) represents an order-of-magnitude estimate.

The result (5.3) is interpreted in the following way: The fact that there are two regimes, crudely defined by $\lambda \ll d$ and $\lambda \gg d$, can be understood in terms of the electrons' relative response to an incident field at the top of the peaks and the bottom of the troughs. When $\lambda \gg d$ ($r \ll 1$), the electrons at the peaks' tops respond poorly by comparison to the electrons at the bottom of the troughs, simply because the former are confined to the metallic fingers of the grating. On the other hand, when $\lambda \ll d$ ($r \gg 1$), it is obvious that the response of the electrons at the peaks' top is impeded to a much lesser degree by the boundaries of the grating's fingers, while the electrons at the troughs' bottoms respond in about the same manner as in the $\lambda \gg d$ regime. This consideration implies that $R(T/B)$ is smaller for $\lambda \gg d$ than for $\lambda \ll d$, which is born out by (3.3). The fact that in both regimes $R(T/B) \sim \beta^{-1} \ll 1$ is in keeping with the above picture: Since the grating is deep, for normal incidence it is always easier for the electrons to respond when they are located at the bottoms of the troughs than when they are

at the tops of the peaks. Note that these considerations do not depend on g , since they pertain to relative magnitude. It is interesting to notice that the same trends are present in numerical studies of shallow-gratings.¹⁰

6. Discussion and Summary

The main message of this work is that for the very deep sinusoidal grating limit ($\beta \gg 1$), the physics simplifies considerably: By introducing a sequence of reasonable approximations, the problem of inverting the Fresnel matrix (2.6) of order β has been reduced to the calculation of eight matrix elements (3.10). The simplicity of the outcome is in keeping with a related study of the surface-plasmon dispersion for an infinite stack of metallic thin films.⁹

With regard to the surface-plasmon dispersion relation, we find two bands, separated by a frequency band gap given by $\Delta\omega/\omega_p = 0.2$. These two bands represent two classes of localized SP excitations: Those for which the fields are maximized in the troughs and those where the fields are maximized inside the peaks. The latter class of modes correspond to the upper band since they represent an enhanced oscillation of the electrons. This interpretation is in keeping with the interpretation of dispersion branch pairs already observed for shallow gratings. It is also consistent with the analogy of the two-adjacent-band structure of electrons moving in a periodic potential.¹² With regard to the local field enhancement distribution, we find that the field at the bottom of the troughs is always larger than at the tops of the peaks. However, the relative magnitude of the "top/bottom" enhancement exhibits different behavior in the $\lambda \gg d$ and $\lambda \ll d$ regimes. The existence of these regimes reflect primarily the response of the electrons at the

peaks' tops. The electrons there are restricted in their motion by the grating's boundary, and therefore respond poorly when $\lambda \gg d$ and much better when $\lambda \ll d$.

The simple outcome of this study will hopefully stimulate further studies in the same vein. To clarify to what degree the specifics of our results do not depend on an artifact of the approximations, it would be desirable to attempt some refinements, e.g., the straight inversion of the quasi-separable approximation (3.1) or (3.2). Another possibility is to carry out large-scale exact calculations of the SG using the dressed Rayleigh expansion as described in Section 2.³ In particular, it is interesting to substantiate the quantitative values we obtain for the width and gap of the SP bands [Eq. (4.4) and (4.5)]. These results hopefully will generate interest also for corresponding experimental work.

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Appendix A: Plasmon Dispersion Relation for a Shallow Grating Surface

To highlight the particular features of the $\beta \ll 1$ regime and to appreciate the role of the various factors in (2.6), we analyze here the shallow grating ($\beta \ll 1$) SP dispersion relation. The results are not new,^{5,7,8} yet they are obtained here in a direct and transparent manner.

Consider first the case of a flat surface, i.e., $g = 0$ in the notation of Fig. 1. Since¹⁴ $J_\nu(z=0) = \delta_{\nu,0}$, Eq. (2.6) yields $m=l$ and the matrix \underline{M} is diagonal. Consequently, for the determinant of \underline{M} to vanish, Eq. (4.1), one or more of the diagonal elements must vanish. Hence, the dispersion relation reads

$$W_0(l)W_1(l) + k_l^2 = 0 \quad (\text{A.1})$$

or, by inserting the definitions (2.3), (A.1) yields

$$k_l^2 = k^2 \frac{\epsilon_0 \epsilon_1}{\epsilon_0 + \epsilon_1}. \quad (\text{A.2})$$

For a flat surface $d \rightarrow \infty$, i.e. $k_G = 0$, so that $k_l \rightarrow k$ and (A.2) is the well-known dispersion relation.^{7,8} Thus the numerator in (2.6)

involving $W_0(l)W_1(m) + k_l k_m$ entails the retardation effects, namely, that the SP dispersion relation cannot cross the boundaries of the light cone.

Consider now the case of a very shallow grating, i.e., g is finite yet $\beta = gk_G \ll 1$. Here the argument of the Bessel function factor is small, yet finite. Therefore, since¹⁴

$$\begin{aligned} \lim_{z \rightarrow 0} J_n(z) &\approx \left(\frac{z}{v}\right)^n \text{ for } v \neq 0 \\ &\approx 1 \text{ for } v = 0 \end{aligned} \quad (\text{A.3})$$

to first order in β , the only non-diagonal terms that contribute are when $|m-l| \leq 1$. Thus, \underline{M} is tri-diagonal, with a dominating diagonal and

the two first-off-diagonal of order β . The $\beta = 0$ and $\beta \ll 1$ examples discussed so far clearly indicate that the Bessel function factor in (2.6) determines the amount of mixing of the m and l Bragg reflections. The non-vanishing denominator of (2.6) affects only the normalization and the fall-off in m, l rate of $M_{m,l}$.

To determine the conditions for (4.1) to hold when $\beta \ll 1$ is no simple task in general. However, for special $(k, k_{||})$ combinations the problem can be easily solved. Let us thus consider, in particular, the boundary of the first Brillouin zone $k_{||} = k_G/2$ and the crossing of the $l = 0$ and $l = -1$ dispersion curves given by (A.2). If there were not off-diagonal terms in \underline{M} , the crossing of the curves at $k_{||} = k_G/2$ would define a $(k, k_{||})$ point for which (4.1) is satisfied. For finite g , however, the two relevant off-diagonal elements $M_{0,-1}$ and $M_{-1,0}$ change the eigenvalues of \underline{M} . The condition for the perturbed eigenvalues of \underline{M} to vanish [so that (4.1) is satisfied] is therefore that the corresponding determinant vanishes:

$$\begin{vmatrix} M_{00} & M_{0,-1} \\ M_{-1,0} & M_{-1,-1} \end{vmatrix} = 0 \quad (A.4)$$

$k_{||} = k_G/2, \quad \beta \ll 1$

Eq. (A.4) is an equation for k which has two solutions, whose difference is the band gap. This equation can be easily solved provided that at the Brillouin zone boundary ($k_{||} = k_G/2$) we are allowed to neglect retardations, i.e., $k_G \gg k(0), |k(1)|$. In this case, $W_0(0) \sim W_1(-1) \sim W_0(0) \sim W_0(-1) \sim ik_G/2$, and some simple algebra gives the gap frequency $\Delta\omega$ as⁷

$$\frac{\Delta\omega}{\omega_p} = \frac{\pi}{\sqrt{2}} \frac{g}{d} \quad (A.5)$$

Appendix B: Separable Approximation for the Bessel Function Factor in

(2.6)

We derive a separable approximation to the Bessel function factor in the matrix \underline{M} :

$$\begin{aligned} B_{m,l} &= J_{m-l}[g(W_0(l)-W_1(m))] \\ &\approx J_{m-l}[i\beta(|l|-|m|)] \end{aligned} \quad (B.1)$$

which is valid for $\beta \gg 1$ and $|l|, |m| \gg 1$. The second line in (B.1) follows from (4.6). We first analyze (B.1) by considering separately the pertinent asymptotic domains and then introduce a simplifying separable expression.

When $1 \ll |l-m| \ll \beta$, the argument of the Bessel function (B.1) is much larger than its order. Correspondingly, the leading asymptotic term is

$$\begin{aligned} J_n(z) &\approx \left(\frac{2}{\pi z}\right)^{1/2} \cos\left[z - \left(\frac{\nu}{2} + \frac{\pi}{4}\right)\right] \\ \nu &= m-l, \quad z = i\beta(|l|-|m|) \approx g[W_0(l)-W_1(m)] \end{aligned} \quad (B.2)$$

When $\beta \sim |l-m|$, the argument of the Bessel function (B.1) and its order are large and proportional each other. The asymptotic expression in this regime is¹⁴

$$\begin{aligned} J_\nu(\nu z) &\approx \frac{1}{\sqrt{2\pi\nu}} \frac{1}{[1-z^2]^{1/4}} e^{\nu\Psi(z)} + \mathcal{O}(\nu^{-3/2}) \\ \Psi(z) &= \sqrt{1-z^2} + \ln[z/(1+\sqrt{1+z^2})] \end{aligned} \quad (B.3)$$

for $|\arg z| < \pi, \quad \nu \rightarrow \infty$

To apply (B.3) to (B.1), we consider separately the three possible sub-domains: (a) $l, m > 0$ (b) $l, m < 0$, (c) $|l| \gg 1, |m| \gg 1$ and m, l of opposite signs. Using¹⁴ $J_n(z) = (-1)^n J_n(-z)$ and $J_n(-z) = (-1)^n J_n(z)$, a simple analysis gives

$$B_{m,l}^{\pm} = e^{\mp \frac{1}{2} \pi |l-m|} \frac{1}{\sqrt{2\pi |l-m|}} \frac{1}{[1+\beta^2]^{1/4}} e^{|l-m| \eta(\beta)}$$

$$\eta(\beta) = \sqrt{1+\beta^2} + \ln[\beta/(1 + \sqrt{1+\beta^2})] \quad (B.4)$$

where B^+ refers to domain (a) and B^- to domain (b). When l and m have different signs [domain (c)], the argument of the Bessel function (B.1) is much smaller than its order, and hence the corresponding asymptotic expression is¹⁴

$$J_{\nu}(z) \approx \frac{1}{\sqrt{2\pi\nu}} \left(\frac{ez}{2\nu}\right)^{\nu}, \quad \nu = m-l, \quad z = i\beta(|l|-|m|). \quad (B.5)$$

Consequently, $z/\nu = \beta |(\ell+m)/(\ell-m)| \ll 1$ and hence $B_{m,l} \approx 0$ for most of the m, l combinations.

Given (B.2)-(B.5), the approximation

$$J_{m-l}[g(W_0(l)-W_1(m))] \approx \sqrt{\frac{k_G}{2\pi}} \frac{1}{(1+\beta^2)^{1/4}} \frac{1}{[W_0(l)-W_1(m)]^{1/2}} \{\exp(i\phi) + \exp(-i\phi)\}$$

$$\phi = \frac{\eta(\beta)}{k_G} [W_0(l)-W_1(m)] - \left[\frac{(m-l)}{2} + \frac{1}{4}\right]\pi \quad (B.6)$$

unifies all relevant domains.

Appendix C: Reduced Auxiliary Matrix \underline{A}

We calculate some and estimate the remaining matrix elements of the auxiliary matrix \underline{A} defined by

$$A_{i,j} = \sum_{\ell=-\infty}^{\infty} b_i(\ell) a_j(\ell), \quad i,j = 1, \dots, 4 \quad (C.1)$$

where, from (3.1) and (3.3),

$$\begin{aligned} a_1(m) &= W_1(m) \exp[i(W_1(m)(g-n(\beta)/k_G) - \frac{\pi}{4})] \\ b_2(\ell) &= CW_0(\ell) \exp[i(W_0(\ell)(g+n(\beta)/k_G))] \\ a_2(m) &= W_1(m) \exp[i(W_1(m)(g+n(\beta)/k_G) + \pi m + \frac{\pi}{4})] \\ b_2(\ell) &= CW_0(\ell) \exp[i(W_0(\ell)(g-n(\beta)/k_G) - \pi \ell)] \\ a_3(m) &= k_m \exp[i(W_1(m)(g-n(\beta)/k_G) - \frac{\pi}{4})] \\ b_3(\ell) &= Ck_\ell \exp[i(W_0(\ell)(g+n(\beta)/k_G))] \\ a_4(m) &= k_m \exp[i(W_1(m)(g+n(\beta)/k_G) + \pi m + \frac{\pi}{4})] \\ b_4(\ell) &= Ck_\ell \exp[i(W_0(\ell)(g-n(\beta)/k_G) - \pi \ell)] \end{aligned} \quad (C.2)$$

and C is defined in (3.3). Note that in (C.1) all the ℓ -dependence enters via the combination $k_\ell = k_{||} + \ell k_G$ [see (C.2)]. Hence, the summation in (C.1) can be evaluated by using the Poisson formula:¹⁵

$$\sum_{\ell=-\infty}^{\infty} G(y+\ell\Delta) = \frac{1}{\Delta} \sum_{m=-\infty}^{\infty} g(2\pi m/\Delta) e^{-2\pi i m y/\Delta} \quad g(t) = \int_{-\infty}^{\infty} du G(u) e^{i t u} \quad (C.3)$$

with the identifications $y \rightarrow k_{||}$, $\Delta \rightarrow k_G$ and $u \rightarrow k_\ell$. Furthermore, since for most terms in (C.1) $|\ell| \gg 1$, it is justified to evaluate $A_{i,j}$ using the asymptotic expression of $W_j(\ell)$, Eq. (4.6). Keeping the leading term in (4.6) is not sufficient since all references to $k(j)$ enter in the second term. It is therefore the first small connection to $A_{i,j}$, beyond the leading term, that carries all the physics.

Inserting (4.6) into (C.2), it is easily seen that all Fourier transforms $g(u)$ mandated by (C.3) take the form

$$g_{ij}(t) = \int_{-\infty}^{\infty} dk_{\ell} b_i(k_{\ell}) a_j(k_{\ell}) e^{ik_{\ell}t} = \int_{-\infty}^{\infty} dk_{\ell} F_n(k_{\ell}) e^{i[f(k_{\ell}) + k_{\ell}t]} \quad (C.4)$$

for: $i, j = 1, \dots, 4$; $n = 1, \dots, 4$ and $n = \alpha, \beta, \gamma, \delta$.

where

$$\begin{aligned} F_1(k_{\ell}) &= W_0(\ell) W_1(\ell) = C \{-k_{\ell}^2 + \frac{1}{2}[k^2(0) + k^2(1)]\} \\ F_2(k_{\ell}) &= C \{-ik_{\ell}|k_{\ell}| + \frac{1}{2}k^2(0)\text{sgn}(k_{\ell})\} \\ F_3(k_{\ell}) &= C \{-ik_{\ell}|k_{\ell}| + \frac{1}{2}k^2(1)\text{sgn}(k_{\ell})\} \\ F_4(k_{\ell}) &= C\{k_{\ell}^2\} \end{aligned} \quad (C.5)$$

and

$$\begin{aligned} f_{\alpha} &= +\frac{\pi}{4} + W_0(\ell)(g - \eta(\beta)/k_G) + W_1(\ell)[g + \eta(\beta)/k_G] \\ &= \frac{\pi}{4} + 2ig|k_{\ell}| - igk^2(1) \frac{1}{|k_{\ell}|} \\ f_{\beta} &= -\frac{\pi}{4} + W_0(\ell)[g + \eta(\beta)/k_G] + W_1(\ell)[g - \eta(\beta)/k_G] \\ &= -\frac{\pi}{4} + 2ig|k_{\ell}| - igk^2(0) \frac{1}{|k_{\ell}|} \\ f_{\gamma} &= \frac{\pi}{4} + W_0(\ell)[g + \eta(\beta)/k_G] + W_1(\ell)[g + \eta(\beta)] + \pi\ell \\ &= \frac{\pi}{4} - \pi k_{\parallel}/k_G + \pi k_{\ell}/k_G + 4ig|k_{\ell}| - ig[k^2(0) + k^2(1)]/|k_{\ell}| \\ f_{\delta} &= -\frac{\pi}{4} + W_0(\ell)[g - \eta(\beta)/k_G] + W_1(\ell)[g - \eta(\beta)/k_G] - \pi\ell \\ &= -\frac{\pi}{4} + \frac{\pi k_{\parallel}}{k_G} - \frac{\pi k_{\ell}}{k_G} + \frac{1}{\beta k_G} |k_{\ell}| - \frac{1[k^2(0) + k^2(1)]}{4\beta k_G} \frac{1}{|k_{\ell}|} \quad (C.6) \end{aligned}$$

The sixteen Fourier transforms $g_{i,j}(t)$ [Eq.(C.4)] are obtained from all combinations of the F_m and the f_n . The explicit correspondence in (Table 1) is

$$\begin{aligned}
f_\alpha & \text{ with } A_{2,2}, A_{2,4}, A_{4,2}, A_{4,4} \\
f_\beta & \text{ with } A_{1,1}, A_{1,3}, A_{3,1}, A_{3,3} \\
f_\gamma & \text{ with } A_{1,2}, A_{1,4}, A_{3,2}, A_{3,4} \\
f_\delta & \text{ with } A_{2,1}, A_{2,3}, A_{4,1}, A_{4,3}
\end{aligned} \tag{C.7}$$

The procedure of calculating $A_{i,j}$ is now clear. We first evaluate the transforms (C.4) for all t -values mandated by the Poisson formula (C.3), and then sum the contributions. As we now show, these two operations can be carried out in closed form. An important bonus of having analytical expressions is the possibility to identify the dominating matrix elements of \underline{A} .

Combining (C.5) and (C.6) with (4.6) implies that all integrals (C.4) are combinations of¹⁶

$$\int_0^\infty dx x^{\nu-1} \exp\left[\frac{1\mu}{2} \left(x - \frac{\gamma^2}{x}\right)\right] = 2\gamma^\nu e^{\frac{1\pi\nu}{2}} K_{-\nu}(\gamma\mu) \quad (\text{case I})$$

$$\int_0^\infty dx x^{\nu-1} \exp\left[\frac{1\mu}{2} \left(x + \frac{\gamma^2}{x}\right)\right] = i\pi \gamma^\nu e^{\frac{1\pi\nu}{2}} H_{-\nu}^{(1)}(\gamma\mu) \quad (\text{case II})$$

$$\text{for } \text{Im}(\mu) > 0, \quad \text{Im}(\gamma^2\mu) > 0, \quad \text{any } \nu \tag{C.8}$$

where K_ν and $H_\nu^{(1)}$ denote the modified Bessel and Hankel functions of the first kind of order ν , respectively. As will become clear shortly, we shall need only the asymptotic or nearthe origin behavior the Bessel function, given by¹⁴

$$\begin{aligned}
K_{-\nu}(z) & \approx \left[\frac{\pi}{2z}\right]^{1/2} e^{-z} \\
H_{-\nu}^{(1)}(z) & \approx \left[\frac{2}{\pi z}\right]^{1/2} e^{i\left[z + \frac{\pi\nu}{2} - \frac{\pi}{4}\right]} \\
& \text{for } |z| \rightarrow \infty
\end{aligned} \tag{C.9.a}$$

and

$$\begin{aligned}
K_{-\nu}(z) &= \frac{1}{2} \Gamma(\nu) \left(\frac{z}{2}\right)^{-\nu} \\
H_{-\nu}^{(1)}(z) &= -\frac{1}{\pi} \Gamma(\nu) e^{i\pi\nu} \left(\frac{z}{2}\right)^{-\nu} \\
&\text{for } |z| \rightarrow 0.
\end{aligned} \tag{C.9.b}$$

Before proceeding further, we mention that the conditions attached to (C.8), i.e., $\text{Im}(\mu) > 0$, etc. are always fulfilled. Also because the k_ℓ -integration in (C.3) is over the whole k_ℓ -axis while in (C.8) it runs over only half the axis, we subdivide the k_ℓ -integration into $-\infty \leq k_\ell \leq 0$ and $0 \leq k_\ell \leq \infty$. The respective contributions are denoted by the "-" and "+" superscripts in (C.10).

By virtue of (C.8) and (C.9), we obtain now an estimate of the magnitude of $g_{i,j}(t)$ (and therefore of the t -summed expression) by considering the " γ_μ " argument in (C.8). This factor determines the dominating exponential or power in the expression for $g_{i,j}(t)$. Constant phases, etc., are omitted in (C.10), but are included in the final expressions. Straightforward algebra based on (C.3) and (C.6) gives

$$\begin{aligned}
\gamma_\alpha^\pm &= \left[-\frac{ik^2(1)}{2ig \pm t} \right]^{1/2}, \quad (\text{Case II}) \\
\gamma_\alpha^\pm \mu_\alpha^\pm &= 2[(2ig \pm t)(-ik^2(1)g)]^{1/2} \\
&= 2[2g^2k^2(1)]^{1/2} \left(1 \pm \frac{it}{4g}\right) \quad \text{for } g \gg t \\
&= 2[itgk^2(1)]^{1/2} \left(1 \pm \frac{ig}{t}\right) \quad \text{for } g \ll t
\end{aligned}$$

$$\begin{aligned}
\gamma_\beta^\pm &= \left[+\frac{ik^2(0)}{2ig \pm t} \right]^{1/2}, \quad (\text{Case I}) \\
\gamma_\beta^\pm \mu_\beta^\pm &= 2[(2ig \pm t)(ik^2(0)g)]^{1/2}
\end{aligned}$$

$$= 2[-2g^2 k^2(0)]^{1/2} (1 \mp \frac{1}{4g}t) \quad \text{for } g \gg t$$

$$= 2[itgk^2(0)]^{1/2} (1 \pm \frac{1}{t}g) \quad \text{for } g \ll t$$

$$\gamma_Y^\pm = \left[-\frac{ig(k^2(0)+k^2(1))}{4ig \pm t \pm \pi/k_G} \right]^{1/2} \quad (\text{Case II}) \quad \text{for } k < k_p/\sqrt{2}$$

$$\gamma_Y^\pm = \left[+\frac{ig(k^2(0)+k^2(1))}{4ig \pm t \pm \pi/k_G} \right]^{1/2} \quad (\text{Case I}) \quad \text{for } k > k_p/\sqrt{2}$$

$$\gamma_Y^{\pm\pm} = 2[(4ig \pm t \pm \pi/k_G)(-ig(k^2(0) + k^2(1)))^{1/2} \quad \text{for } k < k_p/\sqrt{2}$$

$$= 2[4g^2(k^2(0) + k^2(1))]^{1/2} [1 \mp \frac{1}{8g}(t+\pi/k_G)] \quad \text{for } g \gg t$$

$$= 2[g(t+\pi/k_G)ig(k^2(0) + k^2(1))]^{1/2} [1 \pm \frac{4ig}{t+\pi/k_G}] \quad \text{for } g \ll t$$

$$\gamma_Y^{\pm\mu} = 2[(4ig \pm t \pm \pi/k_G)(+ig(k^2(0) - k^2(1)))^{1/2} \quad \text{for } k_0 > k_p/\sqrt{2}$$

$$= 2[-4g^2(k^2(0) - k^2(1))]^{1/2} [1 \mp \frac{1}{8g}(t+\pi/k_G)] \quad \text{for } g \gg t$$

$$= 2[g(t+\pi/k_G)ig(k^2(0)-k^2(1))]^{1/2} [1 \mp \frac{4ig}{t+\pi/k_G}] \quad \text{for } g \ll t$$

$$\gamma_\delta^\pm = \left[-\frac{1(k^2(0) + k^2(1))}{4\beta k_G [\frac{1}{\beta k_G} \pm t \mp \pi/k_G]} \right]^{1/2} \quad (\text{Case II}) \quad \text{for } k < k_p/\sqrt{2}$$

$$= \left[+\frac{1(k^2(0) + k^2(1))}{4\beta k_G [\frac{1}{\beta k_G} \pm t \mp \pi/k_G]} \right]^{1/2} \quad (\text{Case I}) \quad \text{for } k > k_p/\sqrt{2}$$

$$\gamma_\delta^{\pm\pm} = 2[(\frac{1}{\beta k_G} \pm t \mp \pi/k_G)(-\frac{1}{4\beta k_G}(k^2(0) + k^2(1)))^{1/2} \quad \text{for } k_0 < k_p/\sqrt{2}$$

$$= 2[(\frac{1}{\beta k_G} \pm t \mp \frac{\pi}{k_G})(+\frac{1}{4\beta k_G}(k^2(0) + k^2(1)))^{1/2} \quad \text{for } k_0 > k_p/\sqrt{2}$$

for all t (C.10)

where $k_p = \omega_p/c$ and where the square roots in (C.10) and throughout [Eq. (2.3)] are chosen so that the real or imaginary parts are positive. We have also used in (C.10), and in the rest of this Appendix, $\epsilon_0=1$, and the notation "Cases I and II" are defined in (C.8).

Expressions (C.10) yield a quick order-of-magnitude estimate for $g_{i,j}(t)$. Consider first the $g \gg t$ regime. Since $gk(0) \sim gk(1) \sim gk_p \sim \beta \gg 1$, the elements belonging to classes α , β and γ call for the asymptotic limit (C.9.a), while those of class δ call for the limit (C.9.b). Therefore, the leading t -independent terms in (C.10) yield the following dominating exponents in $g_{i,j}(t)$ (Table 1):

$$\text{class } \alpha \sim e^{2i[2g^2 k^2(1)]^{1/2}}$$

$$\text{class } \beta \sim e^{-2[-2g^2 k^2(0)]^{1/2}}$$

$$\begin{aligned} \text{class } \gamma &\sim e^{2i[4g^2(k^2(0)+k^2(1))]^{1/2}} \text{ for } k \leq k_p/\sqrt{2} \\ &\sim e^{-2[-4g^2(k^2(0) + k^2(1))]^{1/2}} \text{ for } k \geq k_p/\sqrt{2} \end{aligned}$$

$$\text{class } \delta \sim 1$$

$$\text{for } g \gg t.$$

$$(C.11)$$

The symbol "1" in the class- δ entry indicates that no exponential factors appear, only powers. Estimates (C.11) imply that as $\beta \rightarrow \infty$, the class- α elements are always the smallest [$k^2(1) < 0$, always]. The class- γ elements are larger than the class- α elements by a factor $\exp[2i[4g^2 k^2(1)]^{1/2} k^2(0)/k^2(1)] \gg 1$ for $k < k_p/\sqrt{2}$, and by yet a larger factor when $k > k_p/\sqrt{2}$. It is therefore justified to discard (set to zero) the class- α elements for the $g \gg t$ regime.

Consider now the complementary $g \ll t$ regime. Considerations similar to those above yield

$$\begin{aligned}
\text{class } \alpha &= e^{2i[1tgk^2(1)]^{1/2}} \\
\text{class } \beta &= e^{-2[1tgk^2(0)]^{1/2}} \\
\text{class } \delta &= e^{2i[1tg(k^2(0) + k^2(1))]^{1/2}} \quad \text{for } k \leq k_p/\sqrt{2} \\
&= e^{-2[1tg(k^2(0) + k^2(1))]^{1/2}} \quad \text{for } k \geq k_p/\sqrt{2} \\
\text{class } \delta &\sim 1 \\
&\quad \text{for } g \ll t.
\end{aligned} \tag{C.12}$$

Since the real and imaginary parts of the square root are always chosen to be positive, (C.12) clearly indicates that the elements belonging to classes α , β and γ are exponentially small, while the class- δ elements are of the order 1 (i.e., fall off as an inverse power). Therefore, in conjunction with the Poisson sum (C.3), there is a sharp cutoff in the u -summation for the $g_{1,j}(t)$ pertaining to classes α , β and γ , whereas for the class- δ element it is necessary to sum all the way to infinity. The cutoff L (in the u -summation) occurs [from (C.10)] when $2\pi L/k_G = t - 2g$ or $L \approx \beta/\pi \gg 1$. It is sharp in the sense that over a range $\Delta nL \ll 1$ the n -dependent contributions diminish as $e^{-\sqrt{\beta}}$.

The asymptotic ($\beta \gg 1$) vanishing by the class- α elements implies that in the evaluation of \underline{A}^{-1} only the eight elements of classes γ and δ contribute¹⁷. We therefore turn now to the calculation of these entries for a fixed t and then consider the summation mandated by the Poisson formula (C.3). Straightforward algebra gives for the class- γ elements

$$\begin{aligned}
g_{1,2}(t) &= P_Y^>(g, k_{||}) \left[\frac{3}{4}(k^2(0) + k^2(1)) \right] \cos[v_{>}(t)] \\
g_{3,4}(t) &= P_Y^>(g, k_{||}) \left[\frac{1}{4}(k^2(0) + k^2(1)) \right] \cos[v_{>}(t)] \\
g_{1,4}(t) &= P_Y^<(g, k_{||}) \left[\frac{1}{4}(3k^2(0) + k^2(1)) \right] i \sin[v_{<}(t)] \\
g_{3,2}(t) &= P_Y^<(g, k_{||}) \left[\frac{1}{4}(k^2(0) + 3k^2(1)) \right] i \sin[v_{<}(t)] \quad (C.13)
\end{aligned}$$

where the labels $>$ and $<$ refer to the domains where $k \geq k_p/\sqrt{2}$ or $k \leq k_p/\sqrt{2}$, respectively, and

$$\begin{aligned}
P_Y^>(g, k) &= \frac{2C}{k_G} \left[\frac{k^2(0) + k^2(1)}{4} \right] \left[\frac{\pi \exp(i\pi)}{[-4g^2(k^2(0) + k^2(1))]^{1/2}} \right]^{1/2} \\
&\times \exp[i\pi(\frac{1}{4} - k_{||}/k_G)] \exp[-2i[-4g^2(k^2(0) + k^2(1))]^{1/2}] \\
v_{>}(t) &= 2[-4g^2(k^2(0) + k^2(1))]^{1/2} \left[\frac{1}{4g} (t + \pi/k_G) \right] \\
P_Y^<(g, k) &= \frac{2iC}{k_G} \left[-\frac{k^2(0) + k^2(1)}{4} \right]^{1/2} \left[\frac{\pi \exp(-i\pi/2)}{[4g^2(k^2(0) + k^2(1))]^{1/2}} \right]^{1/2} \\
&\times \exp[i\pi(\frac{1}{4} - k_{||}/k_G)] \exp[2i[4g^2(k^2(0) + k^2(1))]^{1/2}] \\
v_{<}(t) &= 2i[4g^2(k^2(0) + k^2(1))]^{1/2} \left[\frac{1}{4g} (t + \pi/k_G) \right] \quad (C.14)
\end{aligned}$$

Note that $v_{>}(t)$ do not depend on g ! Similarly, the class-3 elements

$$\begin{aligned}
g_{2,1}(t) &= P_{\delta}(k_{\parallel}) [2e^{3\pi i/2}(I_3^-(g,t) + I_3^+(g,t)) \\
&\quad + \frac{1}{2}(k^2(0) + k^2(1)) e^{i\pi/2}(I_1^-(g,t) + I_1^+(g,t))] \\
g_{2,3}(t) &= P_{\delta}(k_{\parallel}) [2e^{3\pi i/2}(-1)(I_3^-(g,t) - I_3^+(g,t)) \\
&\quad + \frac{i}{2} k^2(0) e^{i\pi/2}(I_1^-(g,t) - I_1^+(g,t))] \\
g_{4,1}(t) &= P_{\delta}(k) [-2i e^{3\pi i/2}(I_3^-(g,t) - I_3^+(g,t)) \\
&\quad + \frac{i}{2} k^2(1) e^{i\pi/2}(I_1^-(g,t) - I_1^+(g,t))] \\
g_{4,3}(t) &= P_{\delta}(k) 2e^{3\pi i/2}(I_3^-(g,t) + I_3^+(g,t)) , \tag{C.15}
\end{aligned}$$

where

$$\begin{aligned}
P_{\delta}(k) &= C \exp[i(-\frac{\pi}{4} + \pi k_{\parallel}/k_G)] \\
I_n^{\pm}(g,t) &= [\frac{1}{\beta k_G} \pm t \mp \pi/k_G]^n . \tag{C.16}
\end{aligned}$$

Expressions (C.15) and (C.16) are valid for the whole $k \leq k_p$ domains.

The last step is to perform the t -summation implied by (C.3). As pointed out before, for the class- δ elements (C.16), there is a sharp cutoff at $t = 2\pi n/k_G - 2g$, whereas for the class- δ elements (C.18) all values of $t = 2\pi n/k_G$ must be summed. The summations pertaining to (C.13) and (C.15) are simply carried out by using the identities¹⁸

$$I_c(\alpha, \gamma) = \sum_{n=-L}^L e^{-i\gamma n} \cos[\alpha(n+1/2)]$$

$$= \frac{1}{2} e^{+i\gamma/2} \left[\frac{\sin[L(\alpha+\gamma)]}{\sin(\frac{\alpha+\gamma}{2})} + \frac{\sin[L(\alpha-\gamma)]}{\sin(\frac{\alpha-\gamma}{2})} \right]$$

$$I_s(\alpha, \gamma) = \sum_{n=-L}^L e^{-i\gamma n} \sin[\alpha(n+1/2)]$$

$$= \frac{1}{2} e^{+i\gamma/2} \left[\frac{\sin[L(\alpha+\gamma)]}{\sin(\frac{\alpha+\gamma}{2})} - \frac{\sin[L(\alpha-\gamma)]}{\sin(\frac{\alpha-\gamma}{2})} \right]$$

$$I_1(\alpha, \gamma) = \sum_{n=-\infty}^{\infty} e^{-i\gamma n} \frac{1}{\alpha+n}$$

$$= + \frac{\pi e^{+i\alpha\gamma}}{\sin(\alpha\pi)}$$

$$I_3(\alpha, \gamma) = \frac{1}{2} \frac{d^2}{d\alpha^2} I_1(\alpha, \gamma) \quad . \quad (C.17)$$

Using (C.17) in (C.3) gives for the class- γ matrix elements

$$A_{1,2} = P_{\alpha}^{\gamma}(g, k_{||}) \left[\frac{3}{4}(k^2(0)+k^2(1)) \right] I_c(\alpha_{\gamma}, \gamma)$$

$$A_{3,4} = P_{\gamma}^{\gamma}(g, k_{||}) \left[\frac{1}{4}(k^2(0)+k^2(1)) \right] I_c(\alpha_{\gamma}, \gamma)$$

$$A_{1,4} = P_{\gamma}^{\gamma}(g, k_{||}) \left[\frac{1}{4}(3k^2(0)+k^2(1)) \right] i I_s(\alpha_{\gamma}, \gamma)$$

$$A_{3,2} = P_{\gamma}^{\gamma}(g, k_{||}) \left[\frac{1}{4}(k^2(0)+3k^2(1)) \right] i I_s(\alpha_{\gamma}, \gamma) ,$$

where

$$\alpha_{<} = i[k^2(0)+k^2(1)]^{1/2} \pi/k_G \quad \text{for } k < k_p/\sqrt{2}$$

$$\alpha_{>} = [-k^2(0)+k^2(1)]^{1/2} \pi/k_G \quad \text{for } k > k_p/\sqrt{2} \quad (\text{C.18})$$

and

$$\gamma = +2\pi k_{\parallel}/k_G. \quad (\text{C.19})$$

For the class- δ matrix elements we obtain

$$A_{2,1} = 0 \quad [\text{of order } (1/\beta)]$$

$$A_{2,3} = \frac{1}{2} P_{\delta}(k) e^{-1\gamma/2} \left\{ 2(\pi^2 + \gamma^2) \left(\frac{k_G}{2\pi}\right)^2 - k^2(0) \right\}$$

$$A_{4,1} = \frac{1}{2} P_{\delta}(k) e^{-1\gamma/2} \left\{ 2(\pi^2 + \gamma^2) \left(\frac{k_G}{2\pi}\right)^2 - k^2(1) \right\}$$

$$A_{4,3} = 0 \quad [\text{of order } \mathcal{O}(1/\beta)] \quad (\text{C.20})$$

In evaluating (C.20) we used $\alpha = -1/2 + \mathcal{O}(1/\beta) \approx -0.5$ in $I_1(\alpha, \gamma)$ and $I_3(\alpha, \gamma)$ of Eq. (C.17), and γ is defined in (C.19). Note that $A_{4,1}$ never vanishes and $A_{2,3}$ vanishes along a curve within the light cone $k(0) = k_{\parallel}$.

Appendix D: Local Field Enhancement

Our starting point is the projection of the slow component in the field, $\vec{E}_g(x,z)$ [EQ. (5.1)], along a vector \hat{v} , which is either \hat{x} or \hat{z} . From (5.1), (3.16) and (C.20) one observes

$$\begin{aligned} \hat{v} \cdot \vec{E}_\Delta(x,z) = \frac{1}{D} \left\{ \sum_{l=-\infty}^{\infty} X_l \mu(l) - \frac{1}{A_{4,1}} \left[\sum_l X_l a_1(l) \right] \left[\sum_l X_l a_1(l) \right] \left[\sum_l b_4(l) \mu(l) \right] \right. \\ \left. - \frac{1}{A_{2,3}} \left[\sum_l X_l a_3(l) \right] \left[\sum_l b_2(l) \mu(l) \right] \right\} \\ X_l = \hat{v} \cdot \hat{p}_{0,+}(l) e^{i[k_l x + W_0(l)z]} \end{aligned} \quad (D.1)$$

For $\beta \gg 1$ and normal incidence ($k_{||} = 0$), the entries to (D.1) are [Eqs. (2.6), (3.3), (4.16) and (C.2)]

$$\begin{aligned} \mu(l) &= - \frac{ik(0)}{\beta^{1/2}} \frac{1}{\sqrt{2\pi}} \frac{1}{\sqrt{|l|}} \exp[-|l|/2\beta] \quad |l| \gg 1 \\ a_1(l) &= ik_G \exp(-i\pi/4) |l| \exp[-|l|/2\beta] \\ a_3(l) &= k_G \exp[-i\pi/4] l \exp[-|l|2\beta] \\ b_2(l) &= C ik_G |l| (-1)^l \exp[-|l|/2\beta] \\ b_4(l) &= C k_G l (-1)^l \exp[-|l|/2\beta] \end{aligned} \quad (D.2)$$

and from (2.3) one deduces¹⁴

$$\mu(0) = + i \exp[-i/gk(0) + \pi/4] \frac{k(0) k(1)}{[k(0) + k(1)]^{3/2}} \frac{1}{\sqrt{2\pi g}} \quad (D.3)$$

We now specialize (D.1) to points T and B in the notation of Fig.

1. Using the definitions (2.3), one obtains

$$\begin{aligned}
X_l(T; \hat{x}) &= - \frac{W_0(l)}{k(0)} \exp[2iW_0(l)g] \\
&= - \Theta([r] - |l|) \exp[2ik(0)g] \\
X_l(T; \hat{z}) &= \frac{k_l}{k(0)} \exp[2iW_0(l)g] \\
&= \frac{l}{r} \Theta([r] - |l|) \exp[2ik(0)g] \\
X_l(B; \hat{x}) &= - \frac{W_0(l)}{k(0)} \exp[ik_l d/2] \approx - \frac{1}{r} |l| (-1)^l \\
X_l(B; \hat{z}) &= \frac{k_l}{k(0)} \exp[ik_l d/2] = \frac{l}{r} (-1)^l
\end{aligned} \tag{D.4}$$

where, for instance, $X_l(T; \hat{x})$ indicates that in (D.1) one substitutes $\hat{v} = \hat{x}$ and the coordinates of point A,

$$r = \frac{k(0)}{k_G} = \frac{\sqrt{\epsilon_0} d}{\lambda}, \tag{D.5}$$

$[r]$ is the integer closest to r from below, and λ is the wavelength of the incident light.

With the help of (D.2), (D.3) and (D.4), the field projections (D.1) can now be calculated in a straightforward manner. Note first that since $b_4(l) = -b_4(-l)$ and $\mu(l) = \mu(-l)$, the term is (4.1) involving $A_{4,1}$ does not contribute. The other terms give

$$\begin{aligned}
\hat{x} \cdot \vec{E}_s(T) &= \frac{1}{D} \left\{ \sum_{l=-\infty}^{\infty} X_l(T, \hat{x}) \mu(l) \right\} \\
\hat{z} \cdot \vec{E}_s(T) &= \frac{1}{D} \left\{ - \frac{1}{A_{2,3}} \left[\sum_l X_l(T, \hat{z}) a_3(l) \right] \left[\sum_l b_2(l) \mu(l) \right] \right\} \\
\hat{x} \cdot \vec{E}_s(B) &= \frac{1}{D} \left\{ \sum_{l=-\infty}^{\infty} X_l(B, \hat{x}) \mu(l) \right\} \\
\hat{z} \cdot \vec{E}_s(B) &= \frac{1}{D} \left\{ - \frac{1}{A_{2,3}} \left[\sum_l X_l(B, \hat{z}) a_3(l) \right] \left[\sum_l b_2(l) \mu(l) \right] \right\},
\end{aligned} \tag{D.6}$$

or explicitly

$$|\hat{x} \cdot \vec{E}_s(T)|^2 = \frac{1}{D^2} \frac{k^2(0)}{2\pi\beta r} \left| \frac{\sqrt{\epsilon_0 \epsilon_1}}{(\sqrt{\epsilon_0} + \sqrt{\epsilon_1})^{3/2}} \right|^2 \quad \text{for } r \ll 1$$

$$= \frac{1}{D^2} \frac{k^2(0)}{2\pi\beta} I_{T,x}^2 \quad \text{for } r \gg 1$$

$$|\hat{z} \cdot \vec{E}_s(T)|^2 = \frac{1}{D^2} \frac{4k^2(0)}{r^2 [\frac{1}{2} - r^2]^2} \frac{I_2^2 I_{T,z}^2}{2\pi\beta}$$

$$|\hat{x} \cdot \vec{E}_s(B)|^2 = \frac{1}{D^2} \frac{k^2(0)}{2\pi\beta} \frac{1}{r^2} I_{B,x}^2$$

$$|\hat{z} \cdot \vec{E}_s(B)|^2 = \frac{1}{D^2} \frac{4k^2(0)}{2\pi\beta} \frac{1}{r^2 (\frac{1}{2} - r^2)^2} I_2^2 I_{B,z}^2 \quad (D.7)$$

where

$$I_2 = \sum_{l=-\infty}^{\infty} \sqrt{|l|} (-1)^l \exp[-|l|/\beta] = \frac{1}{\sqrt{\beta}}$$

$$I_{T,x} = \sum_{|l| > 1}^{[r]} \frac{1}{\sqrt{|l|}} \exp[-|l|/2\beta] = \sqrt{r}, \quad 1 \ll r < 2\beta$$

$$I_{T,z} = \sum_{l=-[r]}^{[r]} l^2 \exp[-|l|/2\beta] = r^3$$

$$I_{B,x} = \sum_{l=-\infty}^{\infty} \sqrt{|l|} (-1)^l \exp[-|l|/2\beta] = \frac{1}{\sqrt{\beta}}$$

$$I_{B,z} = \sum_{l=-\infty}^{\infty} l^2 (-1)^l \exp[-|l|/2\beta] = \beta. \quad (D.8)$$

We added in (D.7) an order-of-magnitude estimate for the various sums.

Using (D.6), we obtain (5.3).

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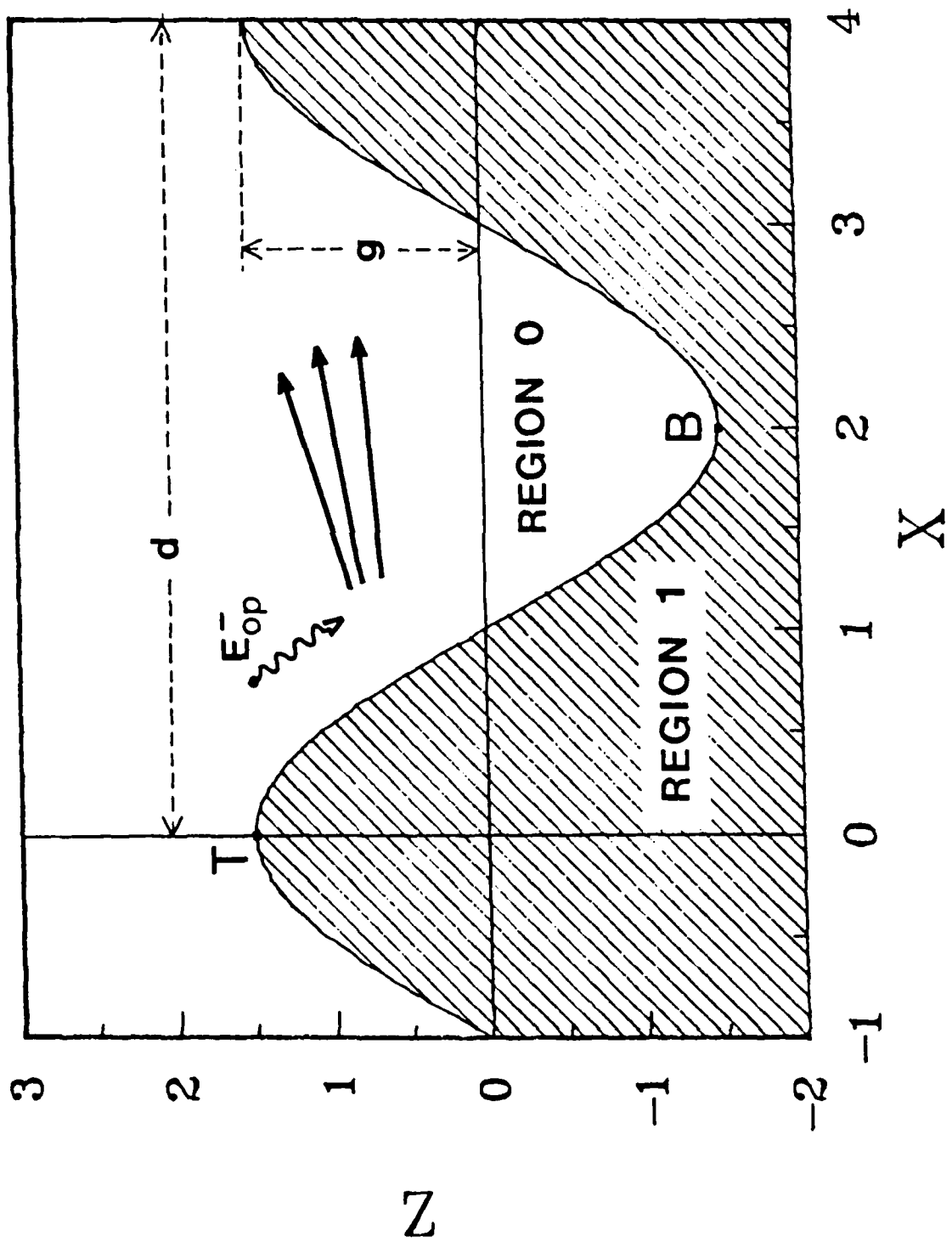
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	1	2	3	4
1	β	γ	β	γ
2	δ	α	δ	α
3	β	γ	β	γ
4	δ	α	δ	α

Table 1: Outlay of the $A_{i,j}$ elements according to the classification defined in Eq. (C.7). The discussion in Appendix C implies that for $\beta \rightarrow \infty$, the class- α terms can be neglected in comparison to the other entries.

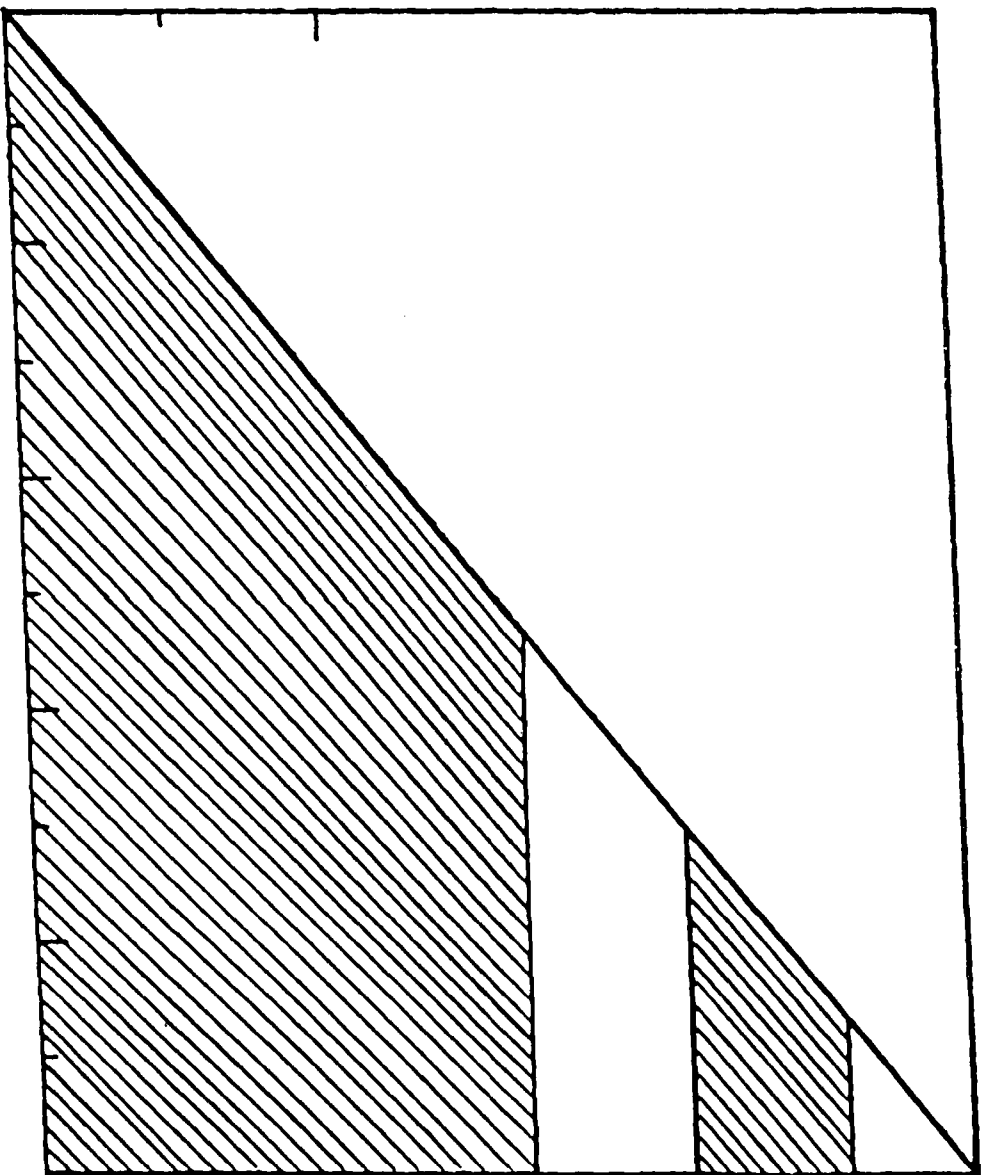
Figure Captions

1. Schematic display of the sinusoidal $[z = g \cos(2\pi x/d)]$ grating and the notation used in this work. The incident light (E_{0p}^-) and the energy Bragg reflection are indicated. The points "T" and "B" are those for which the local field enhancement is evaluated.
2. Display of the surface-plasmon flat bands, Eq. (4.4). The light cone is indicated left of the diagonal line, and $k_p = \omega_p/c$ is the volume plasma wave vector.



$k(0)/k_p$

1
 $\sqrt{3}/2$
 $\sqrt{2}/2$
 $1/2$



$k_{||}$

$k_G/2$

Fig. 2

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